



1. Find a particular solution to the nonhomogeneous equation

$$y''(t) - 2y'(t) + y(t) = \frac{e^t}{1+t^2} = g(t)$$

a) Hom-part

$$y'' - 2y' + y = 0 \Rightarrow y_1 = e^t, y_2 = te^t$$

b) Non-hom part, use variation of constants

$$\therefore y(t) = u y_1 + v y_2 \quad \text{where}$$

$$u = -\int \frac{g y_2}{W} dt, \quad v = \int \frac{g y_1}{W} dt$$

$$\text{Find Wronskian! } W = y_1 y_2' - y_2 y_1' = e^t(e^t + te^t) - te^t(e^t) = e^{2t}$$

$$\Rightarrow u = -\int \frac{t}{1+t^2} dt = -\frac{1}{2} \ln|1+t^2| + A$$

$$v = \int \frac{dt}{1+t^2} = \arctan(t) + B$$

This means the general solution is:

$$y(t) = A e^t + B t e^t + \frac{e^t}{2} \ln|1+t^2| + t e^t \arctan(t)$$

Pick any  $A, B \in \mathbb{R}$  for a solution ▀

2. a) Verify that  $x(t) = \begin{pmatrix} 4 \\ 2 \end{pmatrix} e^{2t}$  satisfies the differential equation

$$x'(t) = \begin{pmatrix} 3 & -2 \\ 2 & -2 \end{pmatrix} x(t)$$

$$\text{RHS} = x' = 2 \begin{pmatrix} 4 \\ 2 \end{pmatrix} e^{2t} = 2x$$

$$\text{LHS} = \begin{pmatrix} 3 & -2 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} 4 \\ 2 \end{pmatrix} e^{2t} = \begin{pmatrix} 12-4 \\ 8-4 \end{pmatrix} e^{2t} = 2 \begin{pmatrix} 4 \\ 2 \end{pmatrix} e^{2t} = 2x = \text{R.H.S.} \quad \checkmark$$

b) Verify that  $\Psi(t) = \begin{pmatrix} e^{-3t} & e^{2t} \\ -4e^{-3t} & e^{2t} \end{pmatrix}$  satisfies the differential equation

$$\Psi'(t) = \begin{pmatrix} 1 & 1 \\ 4 & -2 \end{pmatrix} \Psi(t)$$

$$\text{RHS} = \Psi' = \begin{pmatrix} -3e^{-3t} & 2e^{2t} \\ 12e^{-3t} & 2e^{2t} \end{pmatrix}$$

$$\text{L.H.S.} = \begin{pmatrix} 1 & 1 \\ 4 & -2 \end{pmatrix} \begin{pmatrix} e^{-3t} & e^{2t} \\ -4e^{-3t} & e^{2t} \end{pmatrix} = \begin{pmatrix} (1-4)e^{-3t} & (1+1)e^{2t} \\ (4+8)e^{-3t} & (4-2)e^{2t} \end{pmatrix} = \begin{pmatrix} -3e^{-3t} & 2e^{2t} \\ 12e^{-3t} & 2e^{2t} \end{pmatrix} \quad \checkmark$$

3. Find the general solution of the system of equations

$$\mathbf{x}'(t) = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 1 & -1 \\ -8 & -5 & -3 \end{pmatrix} \mathbf{x}(t)$$

$\mathbf{x}' = A\mathbf{x}$ , we look for solution  $\mathbf{x} = e^{At}$

You can find that the eigen values & eigenvectors of  $A$

are:

$$\lambda_1 = -2, \quad \vec{\lambda}_1 = (-4, 5, 7)$$

$$\lambda_2 = 2, \quad \vec{\lambda}_2 = (0, -1, 1)$$

$$\lambda_3 = -1, \quad \vec{\lambda}_3 = (-3, 4, 2)$$

$$\therefore A = \Lambda^{-1} D \Lambda \quad \text{where } D = \begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{pmatrix} \& \Lambda = \begin{pmatrix} -4 & 0 & -3 \\ 5 & -1 & 4 \\ 7 & 1 & 2 \end{pmatrix}$$

$$\text{Thus } \vec{x} = A \begin{pmatrix} -4 \\ 5 \\ 7 \end{pmatrix} e^{-2t} + B \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} e^{2t} + C \begin{pmatrix} -3 \\ 4 \\ 2 \end{pmatrix} e^{-t}$$

4. For what values of  $\alpha$  is  $\mathbf{x} = \mathbf{0}$  a spiral point.

$$\mathbf{x}'(t) = \begin{pmatrix} 0 & -5 \\ 1 & \alpha \end{pmatrix} \mathbf{x}(t)$$

Spiral point  $\Leftrightarrow \lambda_1 = \bar{\lambda}_2$  &  $\operatorname{Re} \lambda_1 \neq 0$  where  $\lambda_1, \lambda_2$  are eigenvalues of  $A$ . We have  $\vec{x}' = A \vec{x}$

The eigenvalues are

$$\lambda_1 = \frac{1}{2} (\alpha - \sqrt{\alpha^2 - 20}) \quad \& \quad \lambda_2 = \frac{1}{2} (\alpha + \sqrt{\alpha^2 - 20})$$

Since we need  $\lambda_1 = \bar{\lambda}_2$  &  $\operatorname{Re}(\lambda) \neq 0$

$$\Rightarrow \text{we need } \begin{array}{l} \alpha^2 - 20 < 0 \\ \& \\ \alpha \neq 0 \end{array} \Leftrightarrow \alpha \in (-\sqrt{20}, 0) \cup (0, \sqrt{20})$$

5. Find  $A, B \in \mathbb{R}$  such that  $\mathbf{x}(t) = \begin{pmatrix} 1 \\ A \end{pmatrix} e^{-3t} + \begin{pmatrix} 1 \\ B \end{pmatrix} t e^{-3t}$  is a solution to the differential equation

$$\mathbf{x}'(t) = \begin{pmatrix} 1 & -4 \\ 4 & -7 \end{pmatrix} \mathbf{x}(t)$$

↙ L.H.S

Plug & Chug in

$$\mathbf{x}' = -3 \begin{pmatrix} 1 \\ A \end{pmatrix} e^{-3t} + \begin{pmatrix} 1 \\ B \end{pmatrix} e^{-3t} - 3 \begin{pmatrix} 1 \\ B \end{pmatrix} t e^{-3t} = \begin{pmatrix} -2 \\ -3A+B \end{pmatrix} e^{-3t} - \begin{pmatrix} 3 \\ 3B \end{pmatrix} t e^{-3t}$$

$$\text{R.H.S} = \begin{pmatrix} 1 & -4 \\ 4 & -7 \end{pmatrix} \vec{x} = \begin{pmatrix} 1-4A \\ 4-7A \end{pmatrix} e^{-3t} + \begin{pmatrix} 1-4B \\ 4-7B \end{pmatrix} t e^{-3t}, \text{ By comparison, we see}$$

$$\begin{aligned} 1-4A &= -2 \text{ ①} & 1-4B &= -3 \text{ ②} \\ 4-7A &= -3A+B \text{ ③} & 4-7B &= -3B \text{ ④} \end{aligned}$$

system overdetermined  
fingers crossed!

$$A = \frac{3}{4}, B = 1 \text{ by ① \& ②}$$

lets check ③ & ④, ④ is good, ③ is good ✓

$$\therefore \vec{x} = \begin{pmatrix} 1 \\ 3/4 \end{pmatrix} e^{-3t} + \begin{pmatrix} 1 \\ 1 \end{pmatrix} t e^{-3t} \text{ works} \quad \blacktriangledown$$

6. Consider the following differential equation  $y'' + 5y' + 4y = 0$ , for constants  $b, c \in \mathbb{R}$ .

a) Determine a system of equations  $x' = Ax$  that is equivalent to the differential equation.

$$y'' + py' + qy = 0 \iff \vec{x}' = \begin{pmatrix} 0 & 1 \\ -q & -p \end{pmatrix} \vec{x} \quad \text{where } \vec{x} = \begin{pmatrix} y \\ y' \end{pmatrix}$$

It follows by expanding the system  $\rightarrow$

b) Suppose that  $y_1, y_2$  form a fundamental set of solutions for the differential equation, and  $x^{(1)}, x^{(2)}$  form a fundamental set of solutions for the equivalent system. Show that

$$W[y_1, y_2](t) = k W[x^{(1)}, x^{(2)}](t) \text{ for some } k \in \mathbb{R}.$$

(Hint. You don't have to solve for  $y_1, y_2$  or  $x^{(1)}, x^{(2)}$ , but you can if you want to)

$$\text{Let } x^{(1)} = \begin{pmatrix} x_{11} \\ x_{12} \end{pmatrix}, \quad x^{(2)} = \begin{pmatrix} x_{21} \\ x_{22} \end{pmatrix}$$

Since the systems are equivalent,  $y$  must be some linear combination of  $x_{11}$  &  $x_{21}$  (since  $x_1 = y$ ).

$$\begin{aligned} \therefore y_1 &= Ax_{11} + Bx_{21} \quad \text{w/ } A, B, C, D \in \mathbb{C} \\ y_2 &= Cx_{11} + Dx_{21} \end{aligned}$$

$$\text{Note that } \begin{aligned} y_1' &= Ax_{12} + Bx_{22} \quad \text{since } x_2 = y' \\ y_2' &= Cx_{12} + Dx_{22} \end{aligned}$$

$$\therefore \text{ We have } W[x^{(1)}, x^{(2)}] = x_{11}x_{22} - x_{12}x_{21}$$

$$\implies W[y_1, y_2] = y_1 y_2' - y_2 y_1' = (AD - CB) W[x^{(1)}, x^{(2)}]$$

$$\text{i.e. } \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \begin{pmatrix} x_{11} \\ x_{21} \end{pmatrix} \quad \& \quad k = \det \text{ of transformation of } x \rightarrow y$$